

# How various formats can deal with $\text{\LaTeX}$ math

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## Abstract

The purpose of this document is to test  $\text{\LaTeX}$  math in DocOnce with various output formats. Most  $\text{\LaTeX}$  math constructions are rendered correctly by MathJax in plain HTML, but some combinations of constructions may fail. Unfortunately, only a subset of what works in html MathJax also works in sphinx MathJax. The same is true for markdown MathJax expressions (e.g. Jupyter notebooks). Tests and examples are provided to illustrate what may go wrong.

The recommendation for writing math that translates to MathJax in html, sphinx, and markdown is to stick to the environments `\[ ... \]`, `equation`, `equation*`, `align`, `align*`, `alignat`, and `alignat*` only. Test the math with sphinx output; if it works in that format, it should work elsewhere too.

The current version of the document is translated from DocOnce source to the format **pdf $\text{\LaTeX}$** .

## 1 Test of equation environments

### 1.1 Test 1: Inline math

We can get an inline equation `$u(t)=e^{-at}$` rendered as  $u(t) = e^{-at}$ .

### 1.2 Test 2: A single equation with label

An equation with number,

```
!bt
\begin{equation} u(t)=e^{-at} \label{eq1a}\end{equation}
!et
```

looks like

$$u(t) = e^{-at} \tag{1}$$

Maybe this multi-line version is what we actually prefer to write:

```
!bt
\begin{equation}
u(t)=e^{-at}
\label{eq1b}
\end{equation}
!et
```

The result is the same:

$$u(t) = e^{-at} \tag{2}$$

We can refer to this equation through its label `eq1b`: (??).

### 1.3 Test 3: Multiple, aligned equations without label and number

MathJax has historically had some problems with rendering many L<sup>A</sup>T<sub>E</sub>X math environments, but the `align*` and `align` environments have always worked.

```
!bt
\begin{align*}
u(t)&=e^{-at} \\
v(t) - 1 &= \frac{du}{dt}
\end{align*}
!et
```

Result:

$$\begin{aligned} u(t) &= e^{-at} \\ v(t) - 1 &= \frac{du}{dt} \end{aligned}$$

### 1.4 Test 4: Multiple, aligned equations with label

Here, we use `align` with user-prescribed labels:

```
!bt
\begin{align}
u(t)&=e^{-at} \\
\label{eq2b} \\
v(t) - 1 &= \frac{du}{dt} \\
\label{eq3b}
\end{align}
!et
```

Result:

$$u(t) = e^{-at} \quad (3)$$

$$v(t) - 1 = \frac{du}{dt} \quad (4)$$

We can refer to the last equations as the system (??)-(??).

### 1.5 Test 5: Multiple, aligned equations without label

In L<sup>A</sup>T<sub>E</sub>X, equations within an `align` environment is automatically given numbers. To ensure that an html document with MathJax gets the same equation numbers as its latex/pdflatex companion, DocOnce generates labels in equations where there is no label prescribed. For example,

```
!bt
\begin{align}
u(t)&=e^{-at} \\
\\
v(t) - 1 &= \frac{du}{dt} \\
\end{align}
!et
```

is edited to something like

```
!bt
\begin{align}
u(t)&=e^{-at} \\
label_{_auto5}\\
v(t) - 1 &= \frac{du}{dt} \\
label_{_auto6} \\
\end{align}
!et
```

and the output gets the two equation numbered.

$$u(t) = e^{-at} \quad (5)$$

$$v(t) - 1 = \frac{du}{dt} \quad (6)$$

### 1.6 Test 6: Multiple, aligned equations with multiple alignments

The `align` environment can be used with two `&` alignment characters, e.g.

```
!bt
\begin{align}
\frac{\partial u}{\partial t} &= \nabla^2 u, & x \in (0,L), \\
\text{\textbackslash t\in (0,T]} & \\
u(0,t) &= u_0(x), & x \in [0,L] \\
\end{align}
!et
```

The result in pdf<sub>l</sub>atex becomes

$$\frac{\partial u}{\partial t} = \nabla^2 u, \quad x \in (0, L), \quad t \in (0, T] \quad (7)$$

$$u(0, t) = u_0(x), \quad x \in [0, L] \quad (8)$$

A better solution is usually to use an `alignat` environment:

```
!bt
\begin{alignat}{2}
\frac{\partial u}{\partial t} &= \nabla^2 u, & x \in (0, L), \\
\ t \in (0, T] & \\
u(0, t) &= u_0(x), & x \in [0, L] \\
\end{alignat}
!et
```

with the rendered result

$$\frac{\partial u}{\partial t} = \nabla^2 u, \quad x \in (0, L), \quad t \in (0, T] \quad (9)$$

$$u(0, t) = u_0(x), \quad x \in [0, L] \quad (10)$$

## 1.7 Test 7: Multiple, aligned eqnarray equations without label

Let us try the old `eqnarray*` environment.

```
!bt
\begin{eqnarray*}
u(t) &= e^{-at} \\
v(t) - 1 &= \frac{du}{dt} \\
\end{eqnarray*}
!et
```

which results in

$$\begin{aligned} u(t) &= e^{-at} \\ v(t) - 1 &= \frac{du}{dt} \end{aligned}$$

## 1.8 Test 8: Multiple, eqnarrayed equations with label

Here we use `eqnarray` with labels:

```
!bt
\begin{eqnarray}
u(t) &= e^{-at} & \text{label{eq2c}} \\
v(t) - 1 &= \frac{du}{dt} & \text{label{eq3c}} \\
\end{eqnarray}
!et
```

which results in

$$u(t) = e^{-at} \quad (11)$$

$$v(t) - 1 = \frac{du}{dt} \quad (12)$$

Can we refer to the last equations as the system (??)-(??) in the pdf<sub>l</sub>atex format?

## 1.9 Test 9: The `multiline` environment with label and number

The L<sup>A</sup>T<sub>E</sub>X code

```
!bt
\begin{multiline}
\int_a^b f(x)dx = \sum_{j=0}^n \frac{1}{2} h(f(a+jh) +
f(a+(j+1)h)) \\\
=\frac{h}{2}f(a) + \frac{h}{2}f(b) + \sum_{j=1}^n f(a+jh)
\label{multiline:eq1}
\end{multiline}
!et
```

gets rendered as

$$\begin{aligned} \int_a^b f(x)dx &= \sum_{j=0}^n \frac{1}{2} h(f(a+jh) + f(a+(j+1)h)) \\ &= \frac{h}{2}f(a) + \frac{h}{2}f(b) + \sum_{j=1}^n f(a+jh) \end{aligned} \quad (13)$$

and we can hopefully refer to the Trapezoidal rule as the formula (??).

## 1.10 Test 10: Splitting equations using a `split` environment

Although `align` can be used to split too long equations, a more obvious command is `split`:

```
!bt
\begin{equation}
\begin{split}
\int_a^b f(x)dx = \sum_{j=0}^n \frac{1}{2} h(f(a+jh) +
f(a+(j+1)h)) \\\
=\frac{h}{2}f(a) + \frac{h}{2}f(b) + \sum_{j=1}^n f(a+jh)
\end{split}
\end{equation}
!et
```

The result becomes

$$\begin{aligned}\int_a^b f(x)dx &= \sum_{j=0}^n \frac{1}{2}h(f(a+jh) + f(a+(j+1)h)) \\ &= \frac{h}{2}f(a) + \frac{h}{2}f(b) + \sum_{j=1}^n f(a+jh)\end{aligned}\tag{14}$$

### 1.11 Test 11: Newcommands and boldface `bm` vs `pmb`

First we use the plain old `pmb` package for bold math. The formula

```
!bt
\[ \frac{\partial u}{\partial t} +
u \cdot \nabla u = \nu \nabla^2 u -
\frac{1}{\rho} \nabla p, \]
!et
```

and the inline expression `\nabla u(x) \cdot \normalvec` (with suitable newcommands using `pmb`) get rendered as

$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = \nu \nabla^2 \mathbf{u} - \frac{1}{\rho} \nabla p,$$

and  $\nabla \mathbf{u}(\mathbf{x}) \cdot \mathbf{n}$ .

Somewhat nicer fonts may appear with the more modern `\bm` command:

```
!bt
\[ \frac{\partial \bm{u}}{\partial t} +
\bm{u} \cdot \nabla \bm{u} = \nu \nabla^2 \bm{u} -
\frac{1}{\rho} \nabla p, \]
!et
```

(backslash `ubm` is a newcommand for bold math  $u$ ), for which we get

$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = \nu \nabla^2 \mathbf{u} - \frac{1}{\rho} \nabla p.$$

Moreover,

`\nabla \bm{u}(\bm{x}) \cdot \bm{n}`

becomes  $\nabla \mathbf{u}(\mathbf{x}) \cdot \mathbf{n}$ .

## 2 Problematic equations

Finally, we collect some problematic formulas in MathJax. They all work fine in L<sup>A</sup>T<sub>E</sub>X. Most of them look fine in html too, but some fail in sphinx, ipynb, or markdown.

## 2.1 Colored terms in equations

The L<sup>A</sup>T<sub>E</sub>X code

```
!bt
\[\color{blue}\frac{\partial u}{\partial t} +
\nabla\cdot\nabla u = \nu\nabla^2 u -
\frac{1}{\varrho}\nabla p,\]
!et
```

results in

$$\frac{\partial \mathbf{u}}{\partial t} + \nabla \cdot \nabla \mathbf{u} = \nu \nabla^2 \mathbf{u} - \frac{1}{\varrho} \nabla p,$$

## 2.2 Bar over symbols

Sometimes one must be extra careful with the L<sup>A</sup>T<sub>E</sub>X syntax to get sphinx MathJax to render a formula correctly. Consider the combination of a bar over a bold math symbol:

```
!bt
\[\bar{f} = f_c^{-1}f,\]
!et
```

which for pdf<sub>l</sub>atex output results in

$$\bar{f} = f_c^{-1}f.$$

With sphinx, this formula is not rendered. However, using curly braces for the bar,

```
!bt
\[\bar{\mathbf{f}} = f_c^{-1}\mathbf{f},\]
!et
```

makes the output correct also for sphinx:

$$\bar{\mathbf{f}} = f_c^{-1}\mathbf{f},$$

## 2.3 Matrix formulas

Here is an `align` environment with a label and the `pmatrix` environment for matrices and vectors in L<sup>A</sup>T<sub>E</sub>X.

```
!bt
\begin{align}
\begin{pmatrix}
G_2 + G_3 & -G_3 & -G_2 & 0 \\
-G_3 & G_3 + G_4 & 0 & -G_4 \\
-G_2 & 0 & G_1 + G_2 & 0 \\
0 & -G_4 & 0 & G_4
\end{pmatrix}
\end{pmatrix}
\end{align}
!et
```

```

\end{pmatrix}
&=
\begin{pmatrix}
v_1 \\
v_2 \\
v_3 \\
v_4
\end{pmatrix}
+ \cdots
\label{mymatrixeq} \\
\begin{pmatrix}
C_5 + C_6 & -C_6 & 0 & 0 \\
-C_6 & C_6 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0
\end{pmatrix}
\frac{d}{dt} &=
\begin{pmatrix}
v_1 \\
v_2 \\
v_3 \\
v_4
\end{pmatrix} =
\begin{pmatrix}
0 \\
0 \\
0 \\
-i_0
\end{pmatrix}
\end{pmatrix}
\end{align}
!et

```

which becomes

$$\begin{pmatrix} G_2 + G_3 & -G_3 & -G_2 & 0 \\ -G_3 & G_3 + G_4 & 0 & -G_4 \\ -G_2 & 0 & G_1 + G_2 & 0 \\ 0 & -G_4 & 0 & G_4 \end{pmatrix} = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{pmatrix} + \dots \quad (15)$$

$$\begin{pmatrix} C_5 + C_6 & -C_6 & 0 & 0 \\ -C_6 & C_6 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \frac{d}{dt} = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ -i_0 \end{pmatrix} \quad (16)$$

The same matrices without labels in an `align*` environment:

```

!bt
\begin{align*}
\begin{pmatrix}
G_2 + G_3 & -G_3 & -G_2 & 0 \\
-G_3 & G_3 + G_4 & 0 & -G_4 \\
-G_2 & 0 & G_1 + G_2 & 0 \\
0 & -G_4 & 0 & G_4
\end{pmatrix}
&=
\begin{pmatrix}
v_1 \\
v_2
\end{pmatrix}

```



```

v_3 \\
v_4
\end{pmatrix}
+ \cdots \\
\begin{pmatrix}
C_5 + C_6 & -C_6 & 0 & 0 \\
-C_6 & C_6 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0
\end{pmatrix}
\frac{d}{dt} =
\begin{pmatrix}
v_1 \\
v_2 \\
v_3 \\
v_4
\end{pmatrix} =
\begin{pmatrix}
0 \\
0 \\
0 \\
-i_0
\end{pmatrix}
\end{pmatrix}
\end{align*}
!et

```

The rendered result becomes

$$\begin{pmatrix} G_2 + G_3 & -G_3 & -G_2 & 0 \\ -G_3 & G_3 + G_4 & 0 & -G_4 \\ -G_2 & 0 & G_1 + G_2 & 0 \\ 0 & -G_4 & 0 & G_4 \end{pmatrix} = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{pmatrix} + \cdots$$

$$\begin{pmatrix} C_5 + C_6 & -C_6 & 0 & 0 \\ -C_6 & C_6 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \frac{d}{dt} = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ -i_0 \end{pmatrix}$$